

# **Technical data sheet**

# 227CS-024D-02

# Continuous control rotary drive

#### Description

Actuator for adjusting air dampers of  $90^{\circ}$  angle of rotation to be used in HVAC installations.

Torque Motor 2 NmNominal Voltage 24 VAC/DC

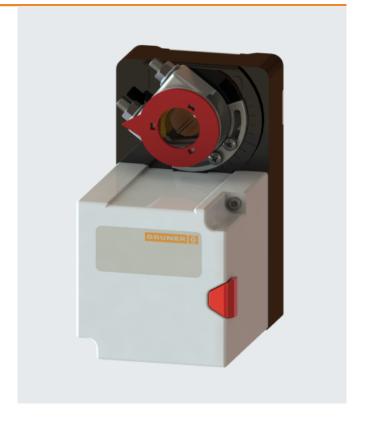
Control Continuous control DC

(0)2...10 V

Damper size up to approx. 0,4 m²

• Damper coupling Clamp

◊ 8-12 mm / Ø 8-16 mm



### Technical data

Electrical data	Nominal voltage	24 VAC/DC
	Nominal voltage range	1929 VAC/DC
	Power consumption motor (motion)	14,0 W
	Power consumption standby (end position)	1,0 W
	Wire sizing	19,0 VA
	Control	Continuous control
		0(2)10 VDC / (0)420 mA / Ri >100 kΩ
	Position feedback	(0)210 VDC, max 5 mA
	Auxiliary switch	-
	Contact load	-
	Switching point	-
	Connection Motor	Cable 1000 mm,
		4 x 0,75 mm <sup>2</sup> (halogen free)
	Connection Auxiliary switch	-
	Connection Position feedback	
	Connection GUAC	-
Functional data	Torque Motor	>2 Nm
	Synchronised speed	-
	Direction of rotation	selected by switch
	Manual override	Gearing latch disengaged with
		pushbutton, self-resetting
	Angle of rotation	0° max. 95°, can be limited with
		adjustable mechanical end stop
	Running time Motor	< 1 s / 90°
	Sound power level Motor	< 45 dB(A)
	Damper coupling	Clamp
		◊ 8-12 mm / Ø 8-16 mm
	Position indication	mechanical with pointer

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#### Technical data

Functional data	Service life	>60'000 cycles (0° - 95° - 0°)
		>1'000'000 partial cycles (max. ±5°)
Safety	Protection class	III (safety extra-low voltage)
	Degree of protection	IP54 (Cable downwards)
	EMC	CE (2004/108/EG)
	LVD	CE (2006/95/EG)
	RoHS	CE (2011/65/EU)
	Mode of operation	Typ 1 (EN 60730-1)
	Rated impulse voltage	0,8 kV (EN 60730-1)
	Control pollution degree	3 (EN 60730-1)
	Ambient temperature normal operation	-30°C+50°C
	Storage temperature	-30°C+80°C
	Ambient humidity	595% relative humidity,
		non condensing (EN 60730-1)
	Maintenance	maintenance free
Dimensions/ Weight	Dimensions	115 x 65 x 89 mm
	Weight	ca. 750 g

#### Operating mode / Properties

# Operating mode

Applying the power supply to BU+BN (1+2) and a reference signal Y to BK (3) of 0(2)...10VDC, moves the actuator to position 1. The actual damper position 0...100% is a feedback signal U for example to share the signal with other actuators.

The actuator is overload-proof, requires no limit switches and stops automatically when the end position is reached.

# **Direct mounting**

Simple direct mounting on the damper spindle with a universal spindle clamp, supplied with an anti-rotation strap to prevent the actuator from rotating.

### Manual override

Manual override is possible with the self-resetting pushbutton (the gearing latch remains disengaged as long as the pushbutton is pressed)

# Mode-switch

DIP-Switch under the case cover

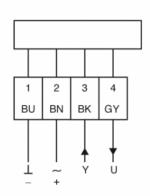
## Adaption drive

Adaptation on angular range < 90°

- -Disconnect the power supply
- -Set the mechanical end stops
- -Connect the actuator to the power supply
- -Put DIP-Switch 4 to "ON"
- -The actuator is adapting on the angular range
- -Put DIP-Switch 4 to "Off"
- -"Y" and "U" signals now refer to the adapted angular range



### Connection / Safety remarks



## Safety remarks

- -Connect via safety isolation transformer -The actuator is not allowed to be used
- outside the specified field of application, especially in airplanes.
- -It may only be installed by suitably trained personnel. Any legal regulations or regulations issued by authorities must be observed during assembly.
- -The device may only be opened at the manufacturer's site.
- -When calculating the required torque, the specifications supplied by the damper manufacturers (cross- section, design, installation site), and the air flow conditions must be observed.
- -The actuator is not allowed to be disposed of as household refuse. All locally valid regulations and requirements must be observed.



### Technical drawing

